

Stand-alone Belt-type Stepless Speed Changer

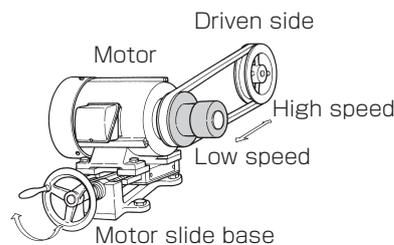
P

| | |
|-------------------------------|---------------------------|
| Standard applied motor output | 0.2 kW to 3.7 kW (4-pole) |
| Speed change ratio | Approx. 1:1.5 |
| External pulley diameter | 86 mm to 218 mm |

A VARI-DIA Pulley Using a Standard V-Belt



- Using a Standard V-Belt
- A Cam Mechanism Prevents Slip
- An Adapter Facilitates Mounting



Specifications

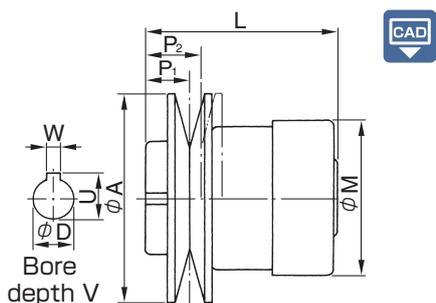
| Model | Motor in use (4P) | Speed change ratio | Belt | Transmission capacity [kW] | | | Mass [kg] |
|-----------|-------------------|--------------------|------|----------------------------|--------------------|-----------|-----------|
| | | | | High speed | Intermediate speed | Low speed | |
| P - 86-MA | 0.2 ~ 0.4 kW | 1:1.5 | A | 0.7 | 0.4 | 0.3 | 1.1 |
| P - 98-MA | 0.4 ~ 0.75 kW | 1:1.4 | A | 1.2 | 0.7 | 0.4 | 1.8 |
| P-106-MA | 0.4 ~ 0.75 kW | 1:1.6 | B | 1.3 | 0.9 | 0.6 | 2.0 |
| P-124-MA | 0.75 ~ 1.5 kW | 1:1.5 | B | 1.8 | 1.2 | 0.8 | 3.0 |
| P-164-MA | 1.5 ~ 2.2 kW | 1:1.5 | C | 3.2 | 2.2 | 1.2 | 6.0 |
| P-218 | 2.2 ~ 3.7 kW | 1:1.4 | C | 6.2 | 4.4 | 3.2 | 14.0 |

Driven Side Rotation Speed

(Rotation speed by driven pulley diameter when mounted to a 4-pole motor) 50 Hz, 1430 min⁻¹ 60 Hz, 1720 min⁻¹ Unit [min⁻¹]

| Model | | 4 in. | 6 in. | 8 in. | 10 in. | 12 in. | 14 in. | 16 in. | 18 in. |
|-----------|------|-------------|------------|------------|-------------|------------|------------|-----------|-----------|
| P - 86-MA | 50Hz | 785 ~ 1180 | 510 ~ 765 | 375 ~ 560 | | | | | |
| | 60Hz | 945 ~ 1420 | 610 ~ 920 | 450 ~ 675 | | | | | |
| P - 98-MA | 50Hz | 970 ~ 1365 | 630 ~ 880 | 460 ~ 650 | | | | | |
| | 60Hz | 1165 ~ 1645 | 755 ~ 1060 | 555 ~ 780 | | | | | |
| P-106-MA | 50Hz | | 585 ~ 950 | 425 ~ 690 | | | | | |
| | 60Hz | | 705 ~ 1150 | 510 ~ 830 | | | | | |
| P-124-MA | 50Hz | | 760 ~ 1140 | 560 ~ 840 | 440 ~ 665 | | | | |
| | 60Hz | | 910 ~ 1370 | 670 ~ 1010 | 530 ~ 800 | | | | |
| P-164-MA | 50Hz | | | 720 ~ 1120 | 570 ~ 885 | 475 ~ 735 | | | |
| | 60Hz | | | 865 ~ 1350 | 685 ~ 1065 | 570 ~ 885 | | | |
| P-218 | 50Hz | | | | 890 ~ 1205 | 740 ~ 1000 | 625 ~ 850 | 545 ~ 740 | 485 ~ 660 |
| | 60Hz | | | | 1070 ~ 1445 | 890 ~ 1205 | 750 ~ 1020 | 655 ~ 890 | 585 ~ 790 |

Dimensions



| Model | Unit [mm] | | | | | | | | | | | | | | | | | |
|----------|-----------|----------------|----------------|-----|-----|----|-----|---|---|-----------|-----------|-------------------|-----|----|----|--|--|--|
| | A | P ₁ | P ₂ | L | M | D | W | U | V | Max. P.D. | Min. P.D. | Movement distance | | | | | | |
| P-86-MA | 86 | 18 | 21.5 | 78 | 63 | 11 | 14 | — | — | — | — | 30 | 77 | 51 | 20 | | | |
| P-98-MA | 98 | 19 | 22.5 | 85 | 73 | 14 | 19 | 5 | 6 | 16 | 21.5 | 40 | 89 | 62 | 21 | | | |
| P-106-MA | 106 | 21 | 26 | 96 | 73 | 14 | 19 | 5 | 6 | 16 | 21.5 | 40 | 95 | 58 | 29 | | | |
| P-124-MA | 124 | 22 | 27 | 101 | 84 | 19 | 24 | 6 | 8 | 21.5 | 27 | 50 | 113 | 75 | 30 | | | |
| P-164-MA | 164 | 25 | 32 | 130 | 102 | 24 | *28 | 8 | 8 | 27 | 31 | 50 | 150 | 96 | 42 | | | |
| P-218 | 218 | 27 | 34 | 163 | 132 | 28 | | 8 | | 31 | 60 | 204 | 150 | 42 | | | | |

* Movement distance refers to a distance to move the motor that is required to change speed.
 * If a repeated load (brake, motor, etc.) is imposed, specify the key method.

| Model | Bore depth [mm] | Supported shaft diameters (adapter bore) ϕD [mm] | | | | | | | | | | | | | | |
|----------|-----------------|--|----|----|----|----|----|----|----|----|----|----|----|----|----|--|
| | | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 18 | 19 | 20 | 22 | 24 | 25 | 28 | |
| P-86-MA | 30 | ○ | ○ | ○ | ○ | ○ | ○ | ○ | | | | | | | | |
| P-98-MA | 40 | | ○ | ○ | ○ | ● | ● | ● | ● | ● | | | | | | |
| P-106-MA | 40 | | ○ | ○ | ○ | ● | ● | ● | ● | ● | | | | | | |
| P-124-MA | 50 | | | | | ● | ● | ● | ● | ● | ● | ● | ● | ● | | |
| P-164-MA | 50 | | | | | ● | ● | ● | ● | ● | ● | ○ | ○ | ○ | ▲ | |
| P-218 | 60 | | | | | | | | | | | ○ | ○ | ○ | ○ | |

* Bore marked with symbols above are available. ●, ○, and ○ indicate adapter type, and ▲ indicate straight type.
 * Adapters indicated as ○ do not have a keyway. Before using with a shaft having a key, first remove the key.
 * ○ indicates model that includes an L key, since adapter specifications prevent a parallel key from fitting. Use this L key when mounting.
 * Bore diameters for the L key distinguish between the old JIS and new JIS codes. Specify when ordering.

How to Place an Order

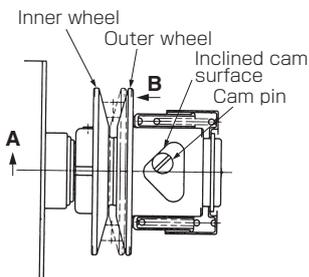
P-86-MA-11
 Size ——— Bore diameter

Cam mechanism

Cam mechanism

The outer wheel (moving wheel) of the speed change pulley is pushed by a spring. However, if the load changes, the tension of the V-belt changes, so the spring is pushed back and the belt moves to the inside, resulting in non-uniform rotation. The P model has a cam mechanism to prevent such non-uniform rotation.

As shown in the figure below, when the motor shaft rotates in the direction of arrow A, the cam pin attached to the main body rotates the outer wheel through the inclined surface of the cam. Accordingly, a force indicated by arrow B increases in proportion to an increase in the load applied to the V-belt and pushes the V-belt out as shown by the virtual line and increases the speed. When a load is not applied, the V-belt is loose and does not apply excessive force to the bearing or other parts. When a load is applied, the V-belt becomes moderately tight and the speed is increased to prevent a slip on the V-pulley and compensates for a decrease in the rotation speed of the motor. Thus, the rotation of the driven shaft can be maintained constant.



Key method with no cam mechanism

A key method is available for applications where an impact load is applied, normal-reverse operation is performed repeatedly, or the device is mounted to the brake motor. For this type, the inner and outer wheels are linked with a sliding key instead of a cam pin, and a strong spring appropriate to the belt's transmission capacity is used. Even if an impact load is applied, it is absorbed by the belt and spring, so excessive force is not applied to the machine.

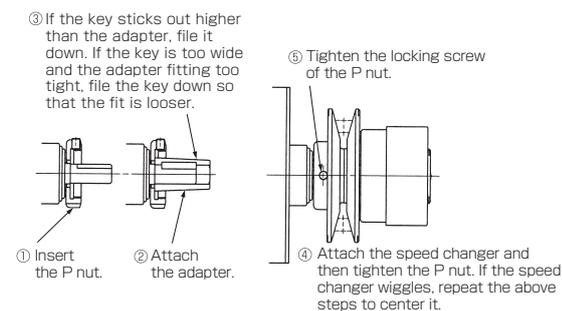
How to Mount to the Motor Shaft

Adapter method

Models using the adapter method use a tapered sleeve (adapter) for mounting the device to motors or other shafts in order to avoid subjecting the speed changer to shock.

Insert the adapter into the tapered hole of the inner wheel and tighten the nut (P nut) to push the adapter in to secure it to the shaft with a wedge effect.

Follow the following procedure to mount the device to the motor shaft.



Straight method

The mounting holes are straight. The device is connected to the motor or other shafts with a standard key and set screws.

When mounting the device, first place the V-belt to the V-groove of the speed change pulley to protect the pulley in order not to give a shock to the speed changer main body, and then apply the device to the pulley shaft end and gently hammer it in place. Firmly tighten the two set screws at two points, one on the keyway and the other one at a right angle to it.

There is a type where the set screws are not visible from the outside. They can be seen by opening the pulley using the belt.

COUPLINGS

ETP BUSHINGS

ELECTROMAGNETIC CLUTCHES & BRAKES

SPEED CHANGERS & REDUCERS

INVERTERS

LINEAR SHAFT DRIVES

TORQUE LIMITERS

ROSTA

SERIES

HOLLOW SHAFT / SOLID SHAFT SPEED CHANGERS AND REDUCERS

BELT-TYPE STEPLESS SPEED CHANGER UNITS

STAND-ALONE BELT-TYPE STEPLESS SPEED CHANGERS

ZERO-MAX (STEPLESS SPEED CHANGERS)

DC MOTORS

ROTATION SPEED INDICATORS

MODELS

- P
- AP
- PL
- PK
- PF
- R/RK/RH
- L
- U
- T